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A distributed algorithm for wide-band radio-interferometry

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Abstract—We propose a scalable, randomised algorithm to solve the inverse imaging problem in wide-band radio-interferometry. In the big-data context of the next-generation radio-telescopes, the scalability is paramount due to the large-scale of the problem to be solved. The proposed method distributes the data measured at each frequency and processes it in parallel. We showcase the algorithm capabilities through realistic simulations.

I. INTRODUCTION

In wide-band radio-interferometry (RI), the electromagnetic signal coming from the sky is probed by an array of antennas, at multiple frequencies ν_i , and is correlated at each antenna pair, producing radio measurements $\mathbf{y}_i \in \mathbb{C}^M$ for each band ν_i . To recover a hyper-spectral image of the sky, an ill-posed problem has to be solved, which under simplifying assumptions, can be modelled as $\mathbf{Y} = \Phi(\mathbf{X}) + \mathbf{N}$, where $\mathbf{Y} = (\mathbf{y}_1, \dots, \mathbf{y}_b) \in \mathbb{C}^{M \times b}$ denotes the wide-band measured data at b bands, corrupted by additive white Gaussian noise $\mathbf{N} = (\mathbf{n}_1, \dots, \mathbf{n}_b) \in \mathbb{C}^{M \times b}$ and $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_b) \in \mathbb{R}_+^{N \times b}$ is the unknown hyper-spectral image. The linear operator $\Phi(\mathbf{X}) = ([\Phi_i \mathbf{x}_i]_{i=1:b})$ models the acquisition process, that is an incomplete Fourier sampling.

II. CONVEX MINIMISATION PROBLEM

We assume a linear mixture model for the image cube and solve a convex minimisation problem imposing low-rankness, joint-sparsity and positivity of the image cube \mathbf{X} [1]. We introduce multiple data fidelity terms defined for each frequency band, to achieve a high degree of parallelism. The minimisation problem can be defined as

$$\min_{\mathbf{X}} f(\mathbf{X}) + \mu g_1(\Psi^\dagger \mathbf{X}) + g_2(\mathbf{X}) + \sum_{i=1}^b h_i(\bar{\Phi}_i(\mathbf{X})), \quad (1)$$

with the functions involved: $f = \iota_{\mathcal{D}}, \mathcal{D} = \mathbb{R}_+^{N \times b}$ accounting for the positivity constraint; $g_1(\mathbf{Z}) = \|\mathbf{Z}\|_{\ell_{2,1}}$ imposing joint-sparsity in a concatenation of wavelet basis Ψ ; $g_2(\mathbf{Z}) = \|\mathbf{Z}\|_*$ imposing low-rankness onto the desired solution; $h_i = \iota_{\mathcal{B}_i}, \mathcal{B}_i = \{\mathbf{Z} \in \mathbb{C}^{M \times b} : \|\mathbf{Z} - \mathbf{Y}_i\|_F \leq \epsilon_i\}$ enforcing data fidelity by constraining the solution to belong to the ϵ_i -balls defined by the known noise statistics. We denote with $\mathbf{Y}_i = (\alpha_1 \mathbf{y}_1, \dots, \alpha_b \mathbf{y}_b) \in \mathbb{C}^{M \times b}$ the measurement matrix active only at the band ν_i such that $\alpha_j = 0, \forall j \neq i$. The associated linear operator is $\bar{\Phi}_i(\mathbf{X}) = ([\alpha_j \Phi_i \mathbf{x}_i]_{i=1:b})$ with $\alpha_j = 0, \forall j \neq i$.

To solve (1), we use a randomised primal-dual algorithm [2] that relies on forward-backward (FB) iterations to manage the non-smooth functions. The algorithmic structure has been employed for distributed, single-band imaging [3] and for non-distributed wide-band imaging [1]. The operations are detailed in Algorithm 1. All the proximal FB steps have closed-form solutions. The proximity operator for the joint-sparsity prior is a row-wise soft-thresholding operation, for row k defined as $(\mathcal{S}_\alpha^{\ell_{2,1}}(\mathbf{Z}))_{k,:} = \frac{\bar{z}(\|\bar{z}\|_{\ell_2} - \alpha)}{\|\bar{z}\|_{\ell_2}}$ if $\|\bar{z}\|_{\ell_2} > \alpha$ and $(\mathcal{S}_\alpha^{\ell_{2,1}}(\mathbf{Z}))_{k,:} = 0$ otherwise. The nuclear norm produces the soft-thresholding of the eigenvalues of \mathbf{Z} , $\mathcal{S}_\alpha^*(\mathbf{Z}) = \mathbf{H}_1 \mathcal{S}_\alpha^{\ell_1}(\Sigma) \mathbf{H}_2^\dagger$. Data fidelity is enforced by the projections $\mathcal{P}_{\mathcal{B}_i}$ onto the ϵ_i sized ℓ_2 balls, for

each band and positivity is imposed via the projection $\mathcal{P}_{\mathcal{D}}$ onto the positive orthant \mathcal{D} .

Algorithm 1 Randomised PD for distributed WB RI.

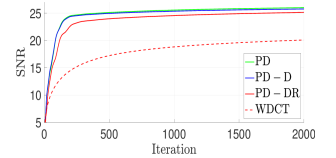
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given  $\mathbf{X}^{(0)}, \bar{\mathbf{X}}^{(0)}, \mathbf{V}_1^{(0)}, \mathbf{V}_2^{(0)}, \mathbf{U}_1^{(0)}, \dots, \mathbf{U}_b^{(0)}, \mu, \tau, \sigma_1, \sigma_2, \sigma_3$ 
repeat for  $t = 1, \dots$ 
    generate active set  $\mathcal{A} \subset \{1, \dots, b\}$ 
    do in parallel
         $\mathbf{V}_1^{(t)} = \mathbf{V}_1^{(t-1)} + \Psi^\dagger \bar{\mathbf{X}}^{(t-1)} - \mathcal{S}_{\mu/\sigma_1}^{\ell_{2,1}}(\mathbf{V}_1^{(t-1)} + \Psi^\dagger \bar{\mathbf{X}}^{(t-1)})$ 
         $\mathbf{V}_2^{(t)} = \mathbf{V}_2^{(t-1)} + \bar{\mathbf{X}}^{(t-1)} - \mathcal{S}_{1/\sigma_2}^*(\mathbf{V}_2^{(t-1)} + \bar{\mathbf{X}}^{(t-1)})$ 
         $\forall i \in \mathcal{A}$  do in parallel
             $\mathbf{U}_i^{(t)} = \mathbf{U}_i^{(t-1)} + \bar{\Phi}_i(\bar{\mathbf{X}}^{(t-1)}) - \mathcal{P}_{\mathcal{B}_i}(\mathbf{U}_i^{(t-1)} + \bar{\Phi}_i(\bar{\mathbf{X}}^{(t-1)}))$ 
        end
    end
     $\mathbf{X}^{(t)} = \mathcal{P}_{\mathcal{D}}\left(\mathbf{X}^{(t-1)} - \tau\left(\sigma_1 \Psi \mathbf{V}_1^{(t)} + \sigma_2 \mathbf{V}_2^{(t)} + \sigma_3 \sum_{i=1}^b \bar{\Phi}_i^\dagger(\mathbf{U}_i^{(t)})\right)\right)$ 
     $\bar{\mathbf{X}}^{(t)} = 2\mathbf{X}^{(t)} - \mathbf{X}^{(t-1)}$ 
until convergence
    
```

III. SIMULATIONS AND RESULTS

We simulate a wide-band image cube following the spectral curvature model $\mathbf{x}_i = \mathbf{x}_0(\nu_i/\nu_0)^{-\gamma + \beta \log(\nu_i/\nu_0)}$, where \mathbf{x}_0 is a 256×256 sized image of a radio region in the M31 galaxy; γ and β are the spectral index maps of size N and modelled as correlated Gaussian random fields. The wide-band cube is generated for $b = 16$ bands in the range $[1.4, 2.8]$ GHz. The wide-band data are simulated using realistic uv -coverages from the VLA array-configuration with $M = 33120$ measurements at each band and are corrupted with zero-mean Gaussian noise with an input signal-to-noise ratio (SNR) of 30 dB.

The figure reveals the SNR evolution for the different algorithms. We can see that the non-distributed primal-dual algorithm denoted by PD [1] and the distributed version PD-D exhibit comparable behaviour, reaching a SNR = 26 dB. For the proposed distributed randomised algorithm PD-DR, we fix the probability of selecting an active subset \mathcal{A} from the full data \mathbf{Y} to 0.5. This has the advantage of lower infrastructure and memory requirements, at the expense of an increased number of iterations to achieve convergence. Also, when compared to the approach proposed in [4] and denoted by WDCT, our proposed algorithm presents superior performance; PD-DR reaches a SNR = 25 dB that is 5 dB higher than WDCT.



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